



Microsoft
Research



Sparsity-based Online Missing Sensor Data Recovery

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May 22, 2012

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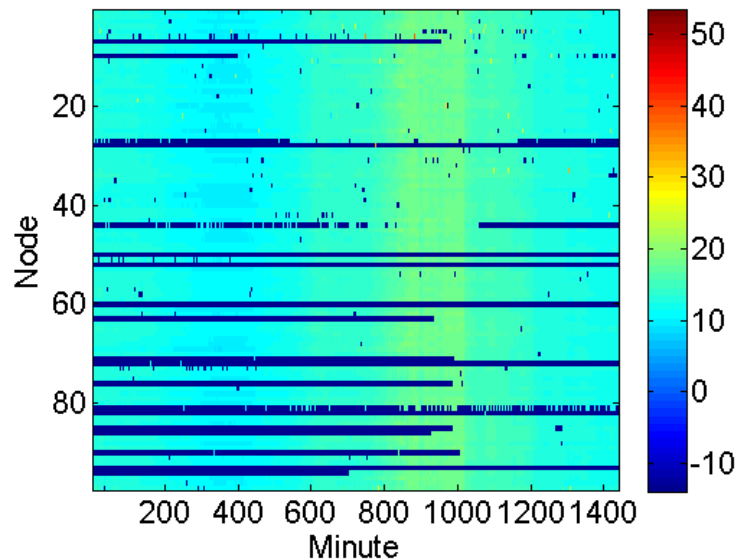
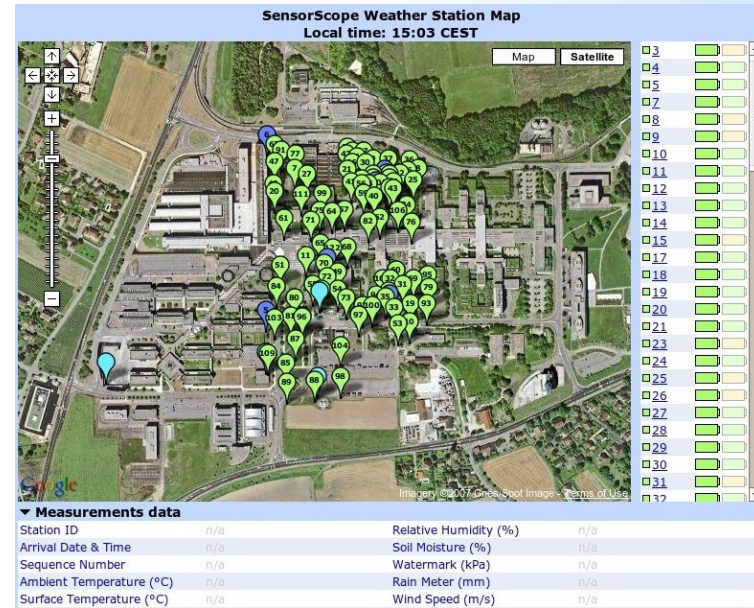
Wireless Sensor Networks

Applications: environment sensing, building, agricultural surveillance, medical care, military

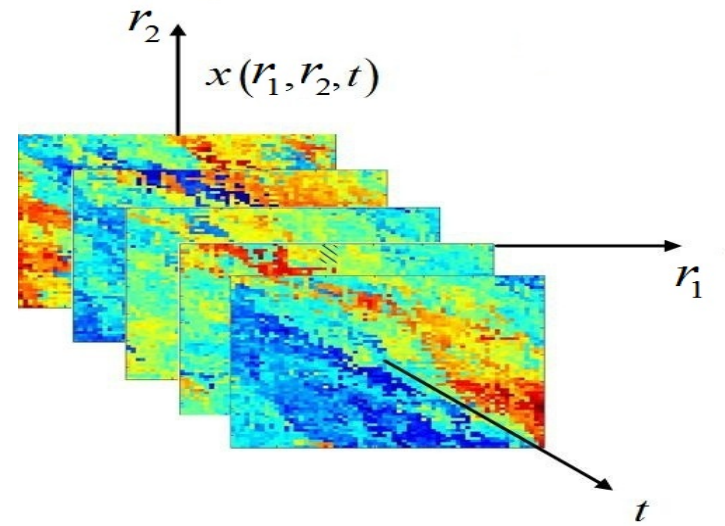


Data is missing

- Node power outage
- Hardware dysfunction
- Channel fading
- Bad environment



dark blue represent missing data



spatial-temporal sampling model

Missing data recovery

➤ **Retransmission:** not suitable to delay sensitive applications

➤ **Interpolation methods: typical ones**

(1) K-Nearest-Neighbor (KNN)

(2) Kriging

Intercommunity: linear combination of available data

Different weight: KNN: distance between neighbors;

Kriging: data statistics (variogram)

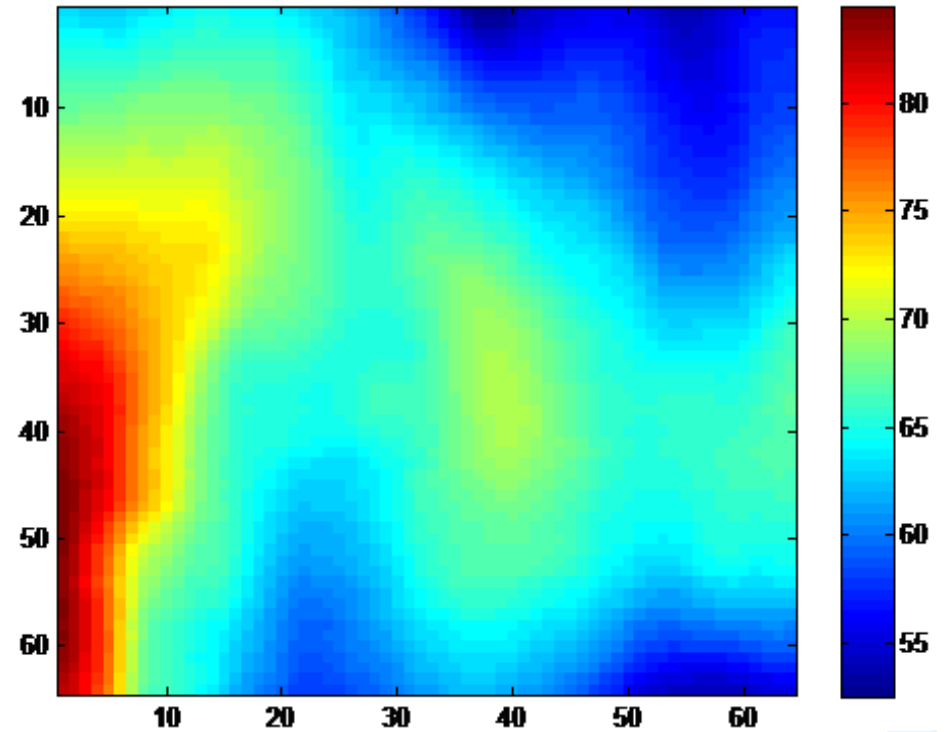
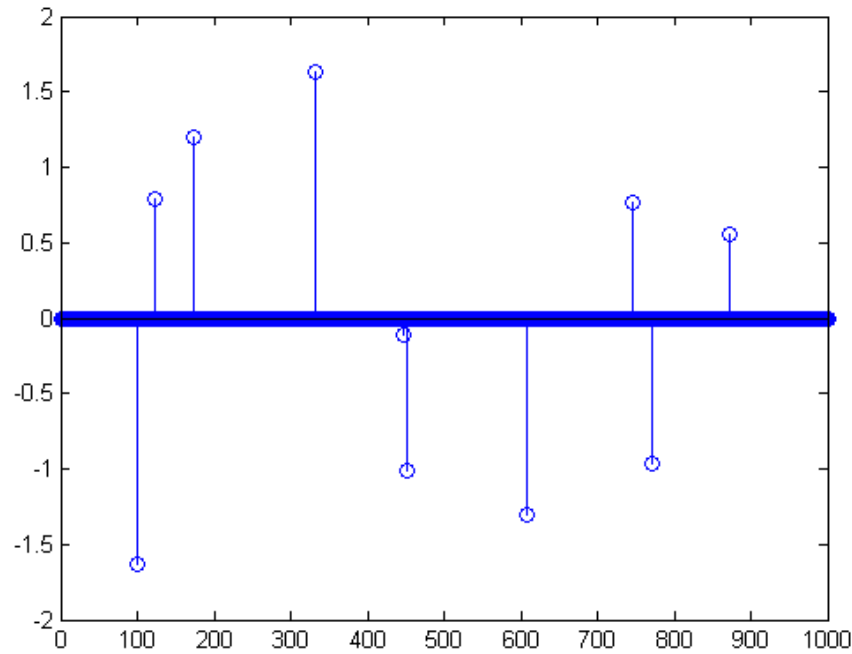
Proposed method

➤ **Sparse linear combination of atoms**

$$\mathbf{x} = \Psi\boldsymbol{\alpha} = \sum_{j=1}^N \psi_j \alpha_j$$

➤ **Weight relies on the available data**

Sparsity



$$\|\alpha\|_0 \ll N, \mathbf{x} \in \mathbb{R}^N$$

$$S/N = 240/4096, \frac{\|\alpha - \alpha_S\|_2^2}{\|\alpha\|_2^2} < 10^{-5}$$

Model

$$\mathbf{f}_n = \Phi_n \mathbf{a}_n \rightarrow \begin{pmatrix} \mathbf{f}_n^{\Lambda_n} \\ \mathbf{f}_n^{\bar{\Lambda}_n} \end{pmatrix} = \begin{pmatrix} \Phi_n^{\Lambda_n} \\ \Phi_n^{\bar{\Lambda}_n} \end{pmatrix} \mathbf{a}_n$$

$$\arg \min_{\mathbf{a}_n} \|\mathbf{a}_n\|_1 \quad \text{s.t.} \quad \mathbf{f}_n^{\Lambda_n} = \Phi_n^{\Lambda_n} \mathbf{a}_n$$

Assumption: Gaussian noise

$$\hat{\mathbf{a}}_n = \arg \min_{\mathbf{a}_n} \frac{1}{2} \left\| \mathbf{f}_n^{\Lambda_n} - \Phi_n^{\Lambda_n} \mathbf{a}_n \right\|_2^2 + \lambda \|\mathbf{a}_n\|_1$$

Output: $\mathbf{A}_n = \Phi_n \hat{\mathbf{a}}_n$

Maximum a posteriori probability

Key: How to reduce recovery error?

(1) Dictionary, (2) Available data consistency

Dictionary

Features of WSN data

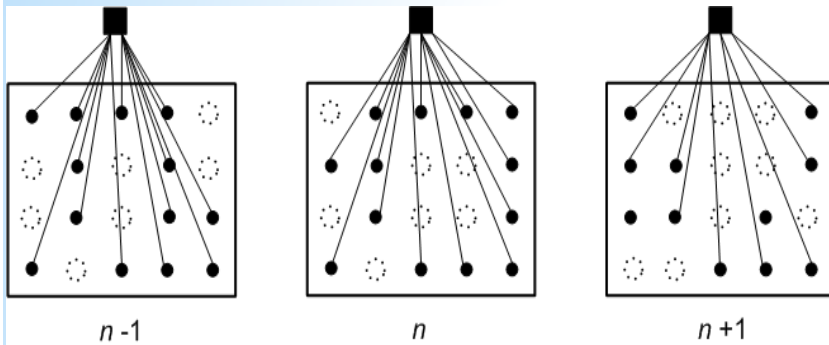
- smooth, few boundaries
- weak spatial correlation
- strong temporal correlation

Example: surface sunshine duration

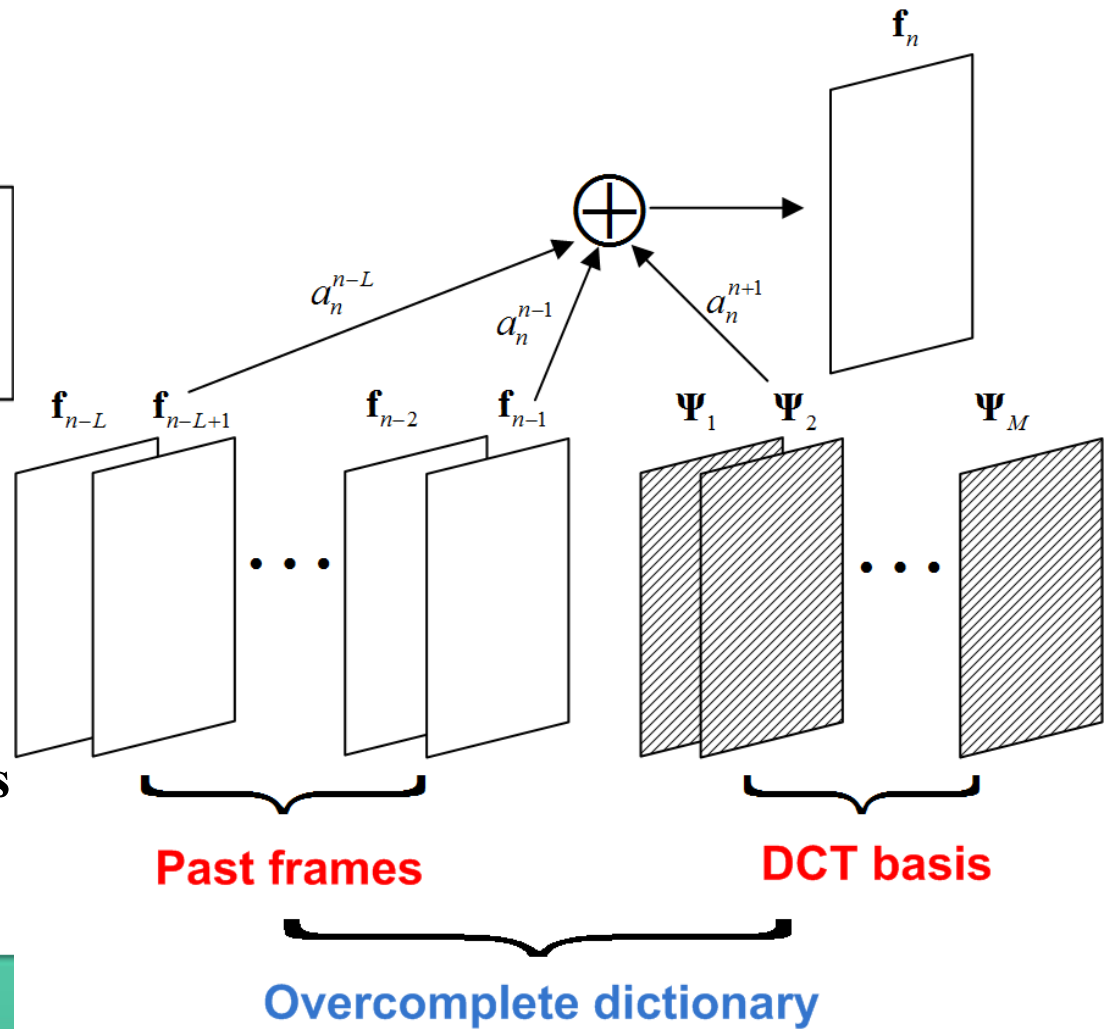


- **Spatial domain: DCT basis**
- **Temporal spatial domain: a few past frames + DCT basis (overcomplete dictionary)**

Sparsity-based online data recovery



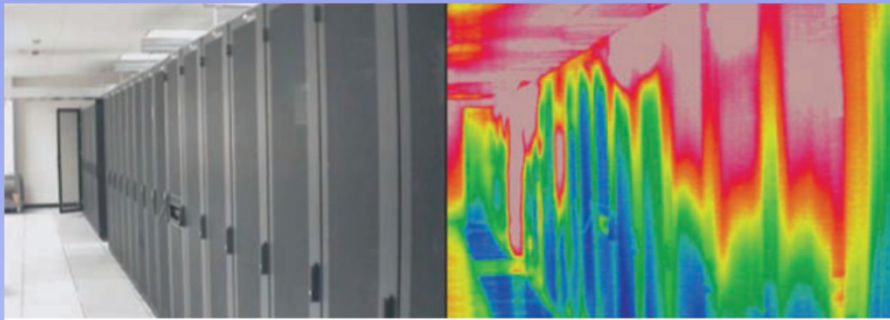
- Sink
- node with observed sample
- node with missing sample



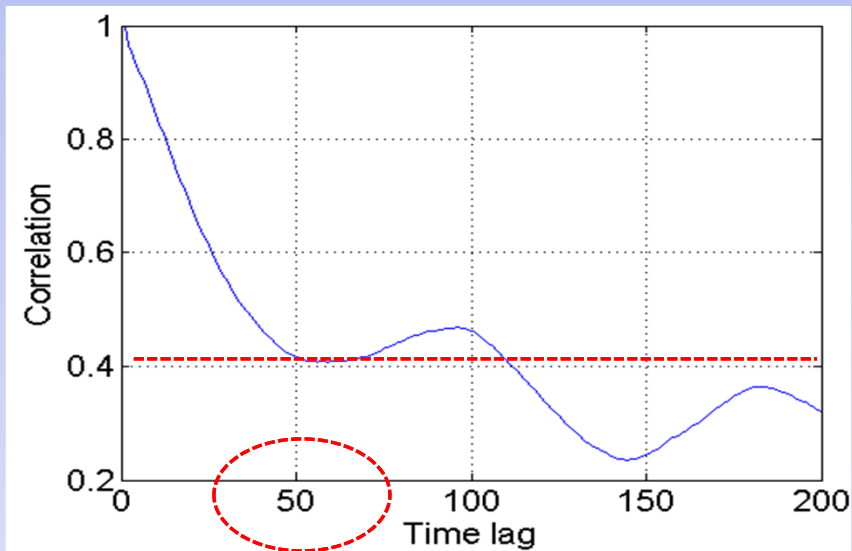
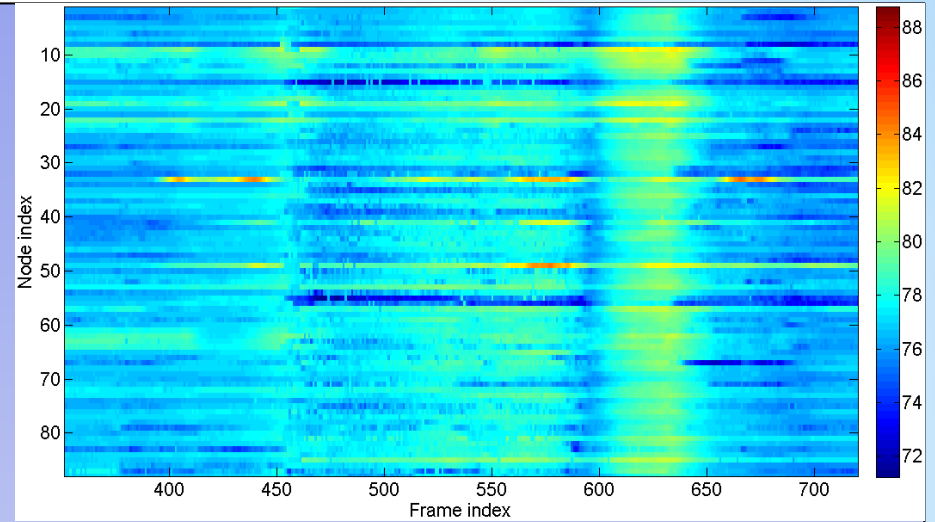
Motivation:
temporal correlation among frames

Proposed approach:

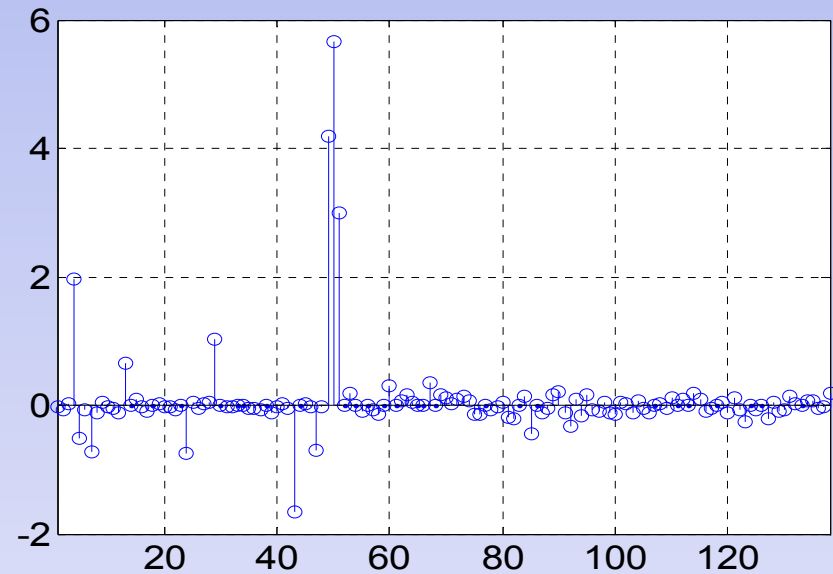
Sparse Recovery using Overcomplete Dictionary (SROD):
Using a sparse linear combination of the overcomplete dictionary to represent the current frame.



**Thermal image of an data center
(data from Microsoft)**



Temporal correlation of frames



Coefficients

Simulation

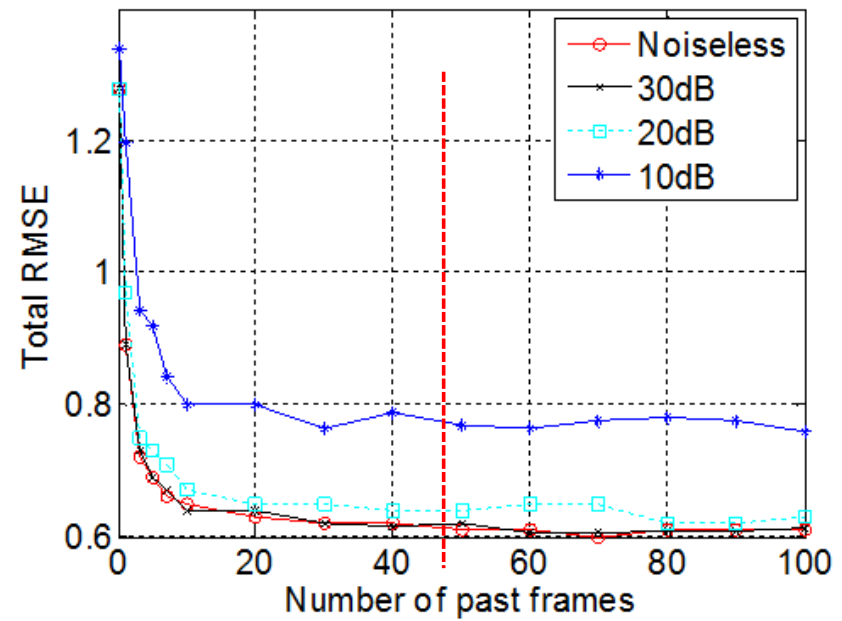
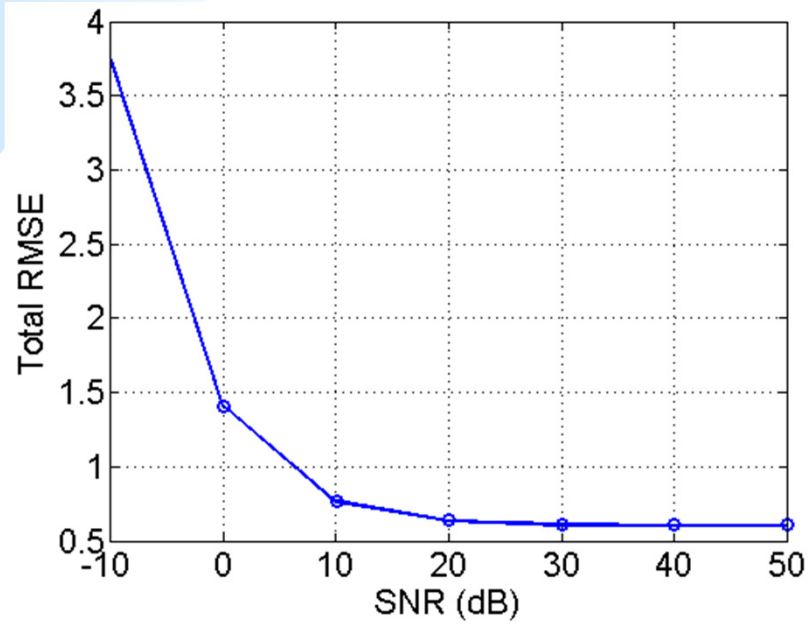
Methods	<i>KNN</i>				<i>SROD</i>			
	10%		20%		10%		20%	
	5	10	5	10	5	10	5	10
MAE_frame	1.31	1.40	1.54	1.88	0.88 (32.8%)	1.11 (20.7%)	1.19 (22.7%)	1.49 (20.7%)
MAE_node	1.48	1.48	1.75	1.80	1.06 (28.4%)	1.21 (18.2%)	1.39 (20.6%)	1.50 (16.7%)
RMSE_frame	0.66	0.69	0.66	0.78	0.43 (34.8%)	0.53 (19.7%)	0.47 (28.8%)	0.58 (25.6%)
RMSE_node	0.68	0.67	0.69	0.77	0.43 (36.8%)	0.52 (23.5%)	0.47 (31.9%)	0.56 (27.3%)
Total RMSE	0.76	0.75	0.73	0.84	0.47 (38.2%)	0.57 (25.0%)	0.51 (30.1%)	0.63 (25.0%)

3D-KNN: anisotropic temporal spatial correlation

Data missing rate: 10%, 20%

Burst missing length: 5, 10

Robustness to Noise

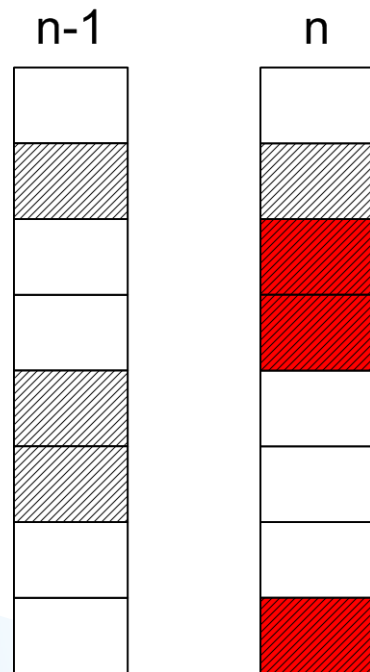


Error propagation

❖ **Problem: the recovery error of last frame may propagate**

❖ **Possible solution:**

Leverage the available data of current frame to correct the recovery error in the last frame in some degree.



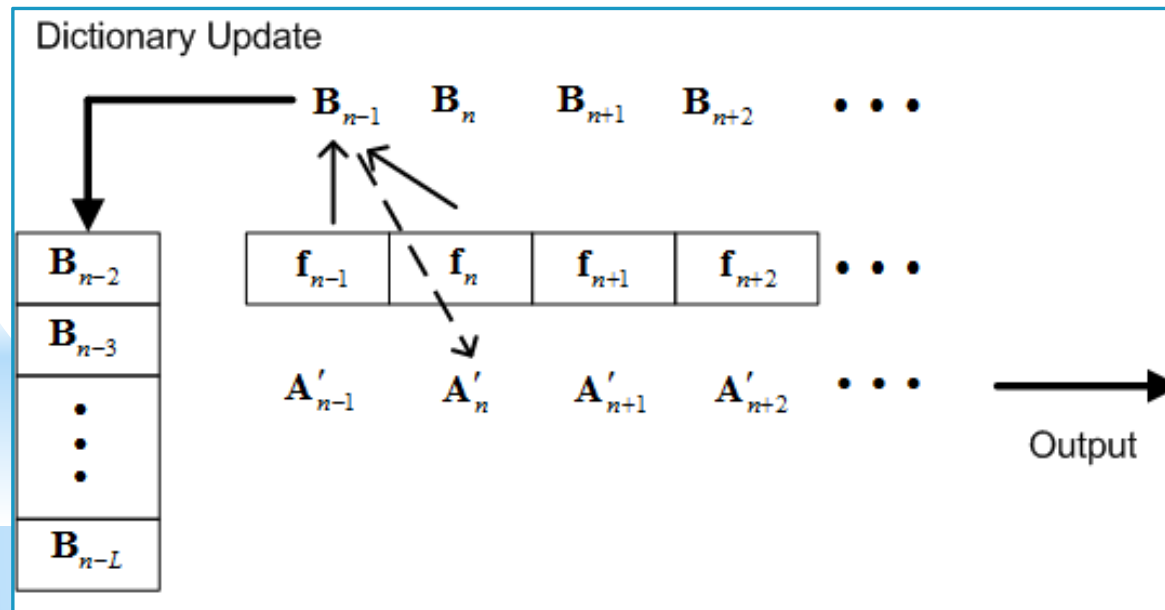
Last frame missing,
but current frame available

Recovery with Corrected Dictionary (RCD)

Neighboring data consistency

$$\hat{\alpha}_{n-1} = \arg \min_{\alpha_{n-1}} \frac{1}{2} \left\| \mathbf{f}_{n-1}^{\Lambda_{n-1}} - \Phi_{n-1}^{\Lambda_{n-1}} \alpha_{n-1} \right\|_2^2 + \lambda \left\| \alpha_{n-1} \right\|_1 + \frac{\mu^2}{2\sigma_n^2} \left\| \mathbf{f}_n^{\bar{\Lambda}_{n-1} \cap \Lambda_n} - \Phi_{n-1}^{\bar{\Lambda}_{n-1} \cap \Lambda_n} \alpha_{n-1} \right\|_2^2$$

Update one atom of the dictionary $\mathbf{B}_{n-1} = \Phi_{n-1} \hat{\alpha}_{n-1}$



\mathbf{B}_{n-1} : updated last frame using RCD

\mathbf{A}'_n : recovered current frame using SROD

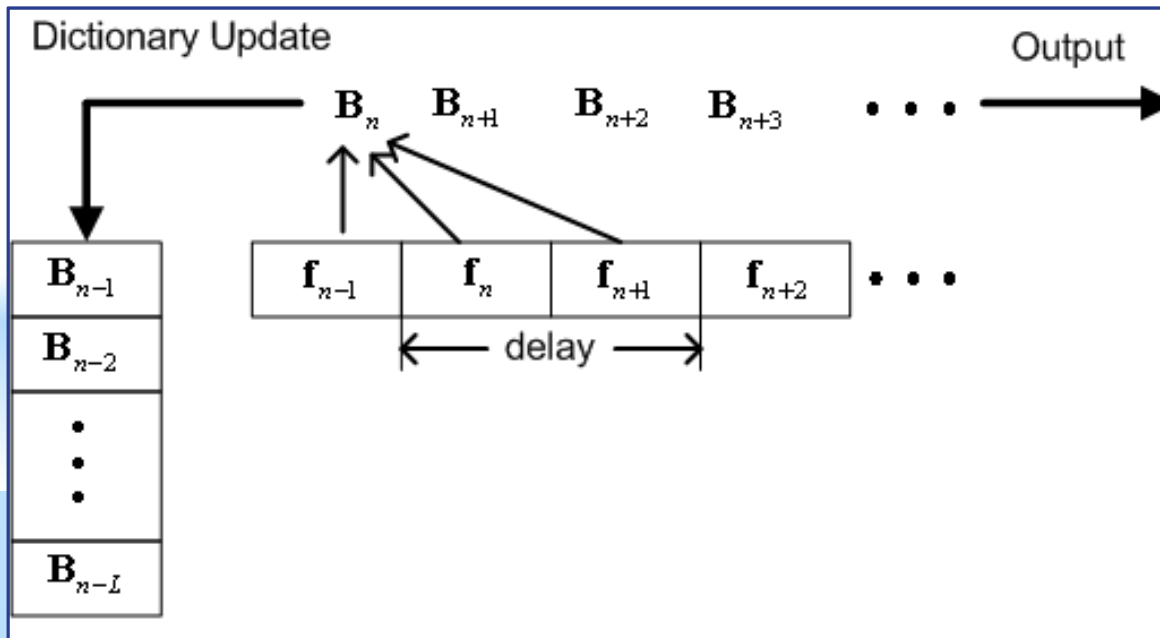
Recovery with future frame compensation (RFFC)

❖ If delay is not a major concern:

Neighboring data consistency

$$\hat{\alpha}_n = \arg \min_{\alpha_n} \frac{1}{2} \left\| \mathbf{f}_n^{\Lambda_n} - \Phi_n^{\Lambda_n} \alpha_n \right\|_2^2 + \lambda \left\| \alpha_n \right\|_1 + \frac{\mu}{2\sigma_{n+1}^2} \left\| \mathbf{f}_{n+1}^{\bar{\Lambda}_n \cap \Lambda_{n+1}} - \Phi_n^{\bar{\Lambda}_n \cap \Lambda_{n+1}} \alpha_n \right\|_2^2$$

Current frame $\mathbf{B}_n = \Phi_n \hat{\alpha}_n$



\mathbf{B}_n : recovered current frame

Simulation

Three proposed sparsity-based recovery method compare with corresponding 3-D KNN

Missing rate: 20%, burst missing length: 1

Methods	<i>KNN</i>			<i>Proposed</i>		
	<i>KNN</i>	<i>KNN-CD</i>	<i>KNN-FFC-1</i>	<i>SROD</i>	<i>RCD</i>	<i>RFFC-1</i>
Mean						
MAE_frame	1.55	1.54 (0.6%)	1.46 (5.8%)	0.97 (37.4%)	0.95 (38.7%)	0.79 (49.0%)
MAE_node	1.80	1.79 (0.6%)	1.73 (3.9%)	1.25 (30.6%)	1.24 (31.1%)	1.08 (40.0%)
RMSE_frame	0.66	0.66 (-)	0.62 (6.1%)	0.38 (42.4%)	0.37 (43.9%)	0.30 (54.5%)
RMSE_node	0.69	0.69 (-)	0.65 (5.8%)	0.39 (43.5%)	0.38 (44.9%)	0.32 (53.6%)
Total RMSE	0.72	0.72 (-)	0.69 (4.2%)	0.43 (40.3%)	0.42 (41.7%)	0.36 (50.0%)

❖ Error reduce by 40%

❖ RFFC reduce error by 10% over SROD

Conclusion

- ❖ **Propose sparsity-based online data recovery method**
- ❖ **Construct an overcomplete dictionary: past frames + DCT basis**
- ❖ **Recovery performance significantly outperforms KNN**
- ❖ **Robust to certain noise**
- ❖ **RCD may reduce error propagation**
- ❖ **RFFC can further improve recovery performance**

Future work

- ❖ **Test missing pattern from the perspective of wireless communication**
- ❖ **Extract data feature using data mining**
- ❖ **Design dictionary and optimization algorithms**

Acknowledgement

Data from
Dr. Jie Liu in Microsoft

Funds from

- Tsinghua-Qualcomm Joint Research Program
- National Natural Science Foundation of China (No. 61001142)
- China Scholarship Council



Thank you

Any questions?